

- IN 3D SPACETIME NEED MATTER FOR DYNAMICS
(BIRKHOFF'S THM, UNIQUENESS OF SCHWARZSCHILD
SOLⁿ AS SOLⁿ of $G_{ab} = 0$)
- WILL RESTRICT MATTER CONTENT TO SINGLE, MASSLESS,
MINIMALLY-COUPLED SCALAR FIELD, ϕ
 - GOOD MODEL PROBLEM FOR STUDYING STRONG-FIELD, RADIATIVE SIT'S - INCLUDING BLACK HOLE FORMATION
 - EXHIBITS INTERESTING PHYSICAL BEHAVIOUR - CRITICAL PHENOMENA - aka BLACK HOLE THRESHOLD PHENOMENA
- WILL REFER TO SYSTEM (SPH. SYMMETRY IMPLICIT) AS EMKA & EKG (EINSTEIN-MASSLESS KLEIN-GORDON)

LAGRANGIAN DENSITY FOR EMKA SYSTEM

$$\begin{aligned}
 \mathcal{L} &= \mathcal{L}_{\text{GRAV}} + \mathcal{L}_{\phi} \\
 &= \sqrt{-g} \left(R - \frac{1}{2} \nabla_a \phi \nabla^a \phi \right)
 \end{aligned}$$

"CONSTRAINT" E.O.M

$$G_{ab} = 8\pi T_{ab} = 8\pi \left(\nabla_a \phi \nabla_b \phi - \frac{1}{2} g_{ab} \nabla_c \phi \nabla^c \phi \right)$$

$$\square \phi = \nabla^a \nabla_a \phi = 0$$

3+1 FORM of SPACETIME METRIC in SS

• COORDINATES (t, r, θ, φ) ADAPTED TO S.S.

METRIC ON UNIT 2-SPHERE $d\Omega^2 = d\theta^2 + \sin^2\theta d\varphi^2$

• THEN MOST GENERAL 3-METRIC IS

$$\gamma_{ij} = \text{diag}(a^2(r,t), r^2 b^2(r,t), r^2 b^2 \sin^2\theta) \quad (1)$$

THE LAPSE FUNCTION IS $\alpha(r,t)$, AND THE SHIFT VECTOR $\beta^i(r,t)$ HAS ONLY A RADIAL COMPONENT, $\beta(r,t)$

$$\beta^i = (\beta, 0, 0) \quad (2)$$

$$\beta_i = \gamma_{ij} \beta^j = (a^2 \beta, 0, 0) \quad (3)$$

• THE MOST GENERAL 4-METRIC IS THEN

$$\begin{aligned} ds^2 &= (-\alpha^2 + \beta^i \beta_i) dt^2 + 2\beta_i dt dx^i + \gamma_{ij} dx^i dx^j \\ &= (-\alpha^2 + a^2 \beta^2) dt^2 + 2a^2 \beta dt dr + a^2 dr^2 + r^2 b^2 d\Omega^2 \quad (4) \end{aligned}$$

• CORRESPONDING EXTRINSIC CURVATURE TENSOR, K^i_j , LIKE γ_{ij} , HAS ONLY TWO INDEPENDENT COMPONENTS

$$K^i_j = \text{diag}(K^r_r(r,t), K^\theta_\theta(r,t), K^\varphi_\varphi) \quad (5)$$

EASE TO SHOW EQUALITY FROM

$$K_{ij} = (\partial_t)^{-1} (-\partial_t \gamma_{ij} + D_i \beta_j + D_j \beta_i)$$

SO, HAVE REDUCED TOTAL # OF GRAVITATIONAL KIN. DIM VOLS FROM 16 TO 6, AND, OF COURSE, THESE VOLS ARE FUNCTIONS ONLY OF (r, t) RATHER THAN (x, y, z, t)

EINSTEIN EQUATIONS(1) CONSTRAINTS

$$R - K^i_i; K^i_i - K^2 = 16\pi \rho \quad (6)$$

$$D_j K^i_j - D_i K = 8\pi j_i \quad (7)$$

NOTE INDEX SHIFT RELATIVE TO PREVIOUS FORM

WHERE $\rho = n_\mu n_\nu T^{\mu\nu} \quad (8)$

$$j_i = \gamma_{ik} j^k = -n_\mu T^{\mu i} \quad (9)$$

RECALL: $n_\mu = (-\alpha, 0, 0, 0) \quad (10)$

(2) EVOLUTION EQUATIONS ($\cdot \equiv \frac{\partial}{\partial t} \equiv \partial_t$)

$$\dot{\gamma}_{ij} = -2\alpha \gamma_{ik} K^k_j + \beta^k \partial_k \gamma_{ij} + \delta_{ik} \partial_j \beta^k + \gamma_{kj} \partial_i \beta^k \quad (11)$$

$$\dot{K}^i_j = \beta^k \partial_k K^i_j - \partial_k \beta^i K^k_j + \partial_j \beta^k K^i_k - D^i D_j \alpha$$

$$+ \alpha (R^i_j + K K^i_j + 4\pi(S - \rho) \delta^i_j - 8\pi S^i_j) \quad (12)$$

WHERE $S_{ij} = T_{ij} \quad (13)$, $S^i_j = \gamma^{ik} S_{kj} \quad (14)$, $S = S^i_i \quad (15)$

NEED CHRISTOFFEL SYMBOLS Γ^i_{jk} , RICCI COMPONENTS R^i_j
 AND RICCI SCALAR R ASSOCIATED WITH g_{ij} (1). USING
 STANDARD FORMULAE AND FOLLOWING NON-VANISHING Γ^i_{jk}
 ($' \equiv \frac{\partial}{\partial r} \equiv \partial_r$)

$$\Gamma^r_{rr} = \frac{a'}{a} \quad \Gamma^r_{\theta\theta} = -\frac{(r^2 b^2)'}{2a^2} \quad \Gamma^r_{\phi\phi} = \sin^2\theta \Gamma^r_{\theta\theta}$$

$$\Gamma^{\theta}_{r\theta} = \Gamma^{\theta}_{\theta r} = \frac{(r^2 b^2)'}{2(r^2 b^2)} \quad \Gamma^{\theta}_{\phi\phi} = -\sin\theta \cos\theta \quad (16a-g)$$

$$\Gamma^{\phi}_{r\phi} = \Gamma^{\phi}_{\phi r} = \Gamma^{\theta}_{r\theta} \quad \Gamma^{\phi}_{\theta\phi} = \Gamma^{\phi}_{\phi\theta} = \cot\theta$$

FROM THESE WE COMPUTE NON-VANISHING R^i_j

$$R^r_r = -\frac{2}{arb} \left(\frac{(rb)'}{a} \right)' \quad (17a)$$

$$R^{\theta}_{\theta} = R^{\phi}_{\phi} = \frac{1}{a(rb)^2} \left(a - \left(\frac{rb}{a} (rb)' \right)' \right) \quad (17b)$$

AND FINALLY, THE SCALAR CURVATURE, R , IS

$$R = R^r_r + R^{\theta}_{\theta} + R^{\phi}_{\phi} = R^r_r + 2R^{\theta}_{\theta}$$

$$\left. \begin{aligned} &= -\frac{2}{arb} \left(\left(\frac{(rb)'}{a} \right)' + \frac{1}{rb} \left(\left(\frac{rb}{a} (rb)' \right)' - a \right) \right) \end{aligned} \right\} \quad (18)$$

IN THE EVALUATION EQUATION FOR K^i_j WE NEED TO
 EVALUATE $D^i D_j \alpha$:

$$D^i D_j \alpha = \gamma^{ik} D_k D_j \alpha = \gamma^{ik} D_k \partial_j \alpha$$

$$= \gamma^{ik} (\partial_k \partial_j \alpha - \Gamma^m_{jk} \partial_m \alpha)$$

USING RESULTS FROM ABOVE, WE FIND

$$D^r D_r \alpha = \frac{1}{a} \left(\frac{\alpha'}{a} \right)' \tag{19a}$$

$$D^\theta D_\theta \alpha = D^\phi D_\phi \alpha = \frac{\alpha'(rb)'}{a^2 rb} \tag{19b}$$

ALSO NEED STRESS-TENSOR "COMPONENTS" J_i, S^i_j

IN SPIRIT OF HAMILTONIAN APPROACH, IT IS CONVENIENT TO INTRODUCE AUXILIARY FUNCTIONS

$$\Phi(r,t) \equiv \phi'(r,t) = \partial_r \phi(r,t) \tag{20}$$

$$\pi(r,t) \equiv \frac{a}{\alpha} (\dot{\phi} - \beta \phi') \tag{21}$$

VIEW Φ, π AS "REAL" DYNAMICAL VOLS FOR SCALAR FIELD; NOTE: FOR MASSLESS FIELD, VALUE OF ϕ IS MEANINGLESS ($\phi \rightarrow \phi + \text{const}$ still satisfies $\square \phi = 0$) ALL "ACTION" IS IN GRADIENTS OF ϕ (I.E. IN Φ AND π)

ALSO NOTE THAT WE HAVE (c/f (a))

$$g_{tt} = -\alpha^2 + a^2 \beta^2$$

$$g_{tr} = g_{rt} = a^2 \beta$$

(22a-c)

$$g_{rr} = a^2$$

$$g_{\theta\theta} = r^2 b^2$$

$$g_{\phi\phi} = r^2 b^2 \sin^2 \theta$$

AND

$$g^{tt} = -\alpha^{-2}$$

$$g^{tr} = g^{rt} = \beta \alpha^{-2}$$

(23a-c)

$$g^{rr} = \alpha^{-2} - \beta^2 \alpha^{-2}$$

$$g^{\theta\theta} = (rb)^{-2}$$

$$g^{\phi\phi} = (rb \sin \theta)^{-2}$$

THEN WE FIND

$$\nabla^t \phi \equiv \partial^{it} \phi = g^{tt} \partial_t \phi + g^{tr} \partial_r \phi = -\frac{\pi}{2a} \quad (24)$$

$$(\nabla^\mu \phi)(\nabla_\mu \phi) = \partial^{i\mu} \phi \partial_{i\mu} \phi = \frac{\bar{\Phi}^2 - \pi^2}{a^2} \quad (25)$$

AND, AGAIN RECALLING THAT $n_\mu = (-\alpha, 0, 0, 0)$, WE FIND

$$\begin{aligned} \rho &= n_\mu n_\nu T^{\mu\nu} = \alpha^2 T^{tt} = \alpha^2 \left(\partial^{it} \phi \partial_{it} \phi - \frac{1}{2} g^{tt} \partial^{i\mu} \phi \partial_{i\mu} \phi \right) \\ &= \frac{\bar{\Phi}^2 + \pi^2}{2a^2} \quad (26) \end{aligned}$$

$$j_i = (j_r, 0, 0)$$

$$j_r = -n_\mu T^{\mu r} = \alpha T^{0r} = \alpha \partial^{it} \phi \partial_{i,r} \phi = -\frac{\bar{\Phi} \pi}{a} \quad (27)$$

FINALLY, WE HAVE THE SPATIAL STRESS COMPONENTS

$$S^i_j = \gamma^{ik} S_{kj} = \gamma^{ik} T_{kj}$$

FROM WHICH WE FIND

$$S^r_r = \rho = \frac{\Phi^2 + \Pi^2}{2a^2} \quad (28)$$

$$S^e_e = S^d_d = \frac{\Pi^2 - \Phi^2}{2a^2} \quad (29)$$

$$S = \rho = 2S^e_e = \frac{\Pi^2 - \Phi^2}{a^2} \quad (30)$$

WE CAN NOW ASSEMBLE THE ABOVE RESULTS TO PRODUCE THE SPHERICALLY-SYMMETRIC SPECIALIZATION OF THE GENERAL 3+1 EQUATIONS (6), (7), (11) & (12)

A) HAMILTONIAN CONSTRAINT

$$R - K^i_j K^j_i + K^2 = 16\pi\rho$$

$$\begin{aligned} -K^i_j K^j_i + K^2 &= -(K^r_r{}^2 + 2K^e_e{}^2) + (K^r_r + 2K^e_e)^2 \\ &= 4K^r_r K^e_e + 2K^e_e{}^2 \end{aligned}$$

$$R + 4K^r_r K^e_e + 2K^e_e{}^2 = 8\pi \frac{\Phi^2 + \Pi^2}{a^2} \quad (31)$$

SEE (18)

B) MOMENTUM CONSTRAINT (ONLY r-COMPONENT IS NON-TRIVIAL)

• FIRST NOTE THAT

$$D_i K^i_r = \partial_i K^i_r + \Gamma^i_{mi} K^m_r - \Gamma^m_{ri} K^i_m$$

$$= K^r_r' + 2\Gamma^e_{re} (K^r_r - K^e_e)$$

$$D_r K = (K^r_r + 2K^e_e)'$$

THEN WE HAVE FROM (2) AND (27)

$$K^e_e' + \frac{(rb)'}{rb} (K^e_e - K^r_r) = 4\pi \frac{\dot{\Phi}}{a} \quad (32)$$

C) EVOLUTION EQUATIONS FOR α, β (a, b)

• FOLLOW DIRECTLY FROM (11), RECALL, CAN BE VIEWED AS DEFⁿ OF K^i_j

$$\dot{a} = -\alpha a K^r_r + (a\beta) \quad (33)$$

$$\dot{b} = -\alpha b K^e_e + \frac{1}{r} (rb) \quad (34)$$

D) EVOLUTION EQUATIONS FOR K^i_j (K^r_r, K^e_e)

• FOLLOW DIRECTLY FROM (12) AND OTHER RESULTS ABOVE

$$K^r_r = \beta K^r_r' - \frac{1}{a} \left(\frac{\alpha'}{a} \right)' + \alpha \left(-\frac{2}{rab} \left(\frac{(rb)'}{a} \right)' + K K^r_r - \frac{8\pi}{a^2} \frac{\dot{\Phi}^2}{a^2} \right) \quad (35)$$

$$\dot{K}_0^0 = \beta K_0^0{}' + \frac{\alpha}{(rb)^2} - \frac{1}{a(rb)^2} \left(\frac{\alpha rb (rb)'}{a} \right)' + \alpha K K_0^0 \quad (36)$$

(31)-(36) ARE THE COMPLETE 3+1 EQUATIONS FOR THE GEOMETRIC VARIABLES (NOTE: WE HAVE SAID NOTHING YET RE COORDINATE CHOICES, I.E. RE SPECIFICATIONS OF α AND β)

MASSLESS KLEIN GORDON EQUATION

WANTED E.O.M. FOR $\bar{\Phi}$ AND π

RECALL DEFⁿ OF π , (23)

$$\pi = \frac{a}{\alpha} (\dot{\Phi} - \beta \Phi')$$

$$\rightarrow \dot{\Phi} = \frac{\alpha}{a} \pi + \beta \Phi' = \frac{\alpha}{a} \pi + \beta \bar{\Phi}$$

BUT $\dot{\Phi}' = \dot{\bar{\Phi}}$, SO

$$\dot{\bar{\Phi}} = \left(\beta \bar{\Phi} + \frac{\alpha}{a} \pi \right)' \quad (37)$$

TO FIND π EQU, RECALL THAT

$$\square \phi = \frac{1}{\sqrt{-g}} \partial_\mu \left(\sqrt{-g} g^{\mu\nu} \partial_\nu \phi \right)$$

$$\square \phi = 0 \rightarrow \partial_\mu \left(\sqrt{-g} g^{\mu\nu} \partial_\nu \phi \right) = 0$$

$$\begin{aligned}
&\rightarrow \partial_t (\sqrt{-g} g^{tt} \partial_t \phi) + \partial_r (\sqrt{-g} g^{rr} \partial_r \phi) \\
&= \partial_t (\alpha a r^2 b^2 (-\alpha^{-2} \dot{\phi} + \beta \alpha^{-2} \phi')) \\
&\quad + \partial_r (\alpha a r^2 b^2 ((\alpha^{-2} - \beta^2 \alpha^{-2}) \phi' + \beta \alpha^{-2} \dot{\phi})) \\
&= 0
\end{aligned}$$

$$\rightarrow (r^2 b^2 \ddot{\pi}) = (r^2 b^2 (\beta \dot{\pi} + \frac{\alpha}{a} \dot{\Phi}))'$$

↳ WRITE AS $(r^2 b^2) \ddot{\pi} + (r^2 b^2) \dot{\pi}$ AND USE
 EVOLUTION EQUATION (39) FOR \dot{b}

$$\begin{aligned}
\ddot{\pi} &= \frac{1}{r^2 b^2} \left(r^2 b^2 \left(\beta \dot{\pi} + \frac{\alpha}{a} \dot{\Phi} \right) \right)' && (38) \\
&\quad + 2 \left(\alpha K^0_0 - \beta \frac{(rb)'}{rb} \right) \dot{\pi}
\end{aligned}$$

CHARACTERISTIC ANALYSIS of THE SCALAR FIELD

REF: COUPANT: HILBERT "METHODS of MATHEM. PHYS",
VOL II, vol 5

- EQNS (37)-(38) ARE A 1ST-ORDER, QUASI-LINEAR SYS FOR OUR RADIATION FIELD. DEFINING

$$u = (\underline{E}, \pi)^T$$

WE CAN WRITE

$$u_t + A u_x = B \quad (39)$$

$$A = - \begin{pmatrix} \beta & \alpha/a \\ \alpha/a & \beta \end{pmatrix} \quad (40)$$

AND B IS A LOWER MATRIX WHICH DOES NOT INVOLVE DERIVATIVES of u .

- THE CHARACTERISTIC DIRECTIONS $\tau = dr/dt$ OF (39)-(40) ARE GIVEN BY

$$|A - \tau I| = 0$$

→

$$\tau = -\beta \pm \frac{\alpha}{a} \quad (41)$$

THESE ARE THE "LOCAL SIGNAL SPEEDS" FOR THE SCALAR FIELD

- MASSLESS SCALAR FIELD - WEAK (LOW-SELF GRAVITATIONAL) SIGNALS TRAVEL ALONG NULL GEODESICS \rightarrow ALTERNATE DERIVATION of (41)

$$ds^2 = -\alpha^2 dt^2 + a^2 (dr + \beta dt)^2 = 0$$

REGULARITY / LOCAL FLATNESS AT $r=0$

- OUR CAUCHY PROBLEM FOR THE EMKG MODEL IS TO BE SOLVED ON

$$t \geq 0, \quad r \geq 0$$

- BOUNDARY CONDITIONS AS $r \rightarrow \infty$ WILL FOLLOW FROM ASYMPTOTIC FLATNESS, NO INCOMING RADIATION; $r=0$ NOT A REAL BOUNDARY, BUT COMPUTATIONALLY (I.E. WHEN FINITE DIFFERENCING) IS EFFECTIVELY ONE

- GET CONDITIONS AT $r=0$ BY DEMANDING THAT SCALAR GRAV. FIELDS BE REGULAR, AND THAT THE S.T. BE LOCALLY FLAT THERE

- TRICKY ISSUE IN GENERAL UNLESS WE MAKE ASSUMPTIONS ABOUT SLICING, SPATIAL COORDINATES (SEE BAROEN; PIRAN, PHYSICS REPORTS 96 (1983) 205-250); WE WILL ASSUME EVERYWHERE SMOOTH SLICINGS AND SPATIAL COORDS

(*) SCALAR FIELD

$$\nabla \phi = \phi' \dot{\tau}$$

NOT DEFINED AT $r=0$ UNLESS

$$\phi'(0, t) = 0 \quad (42)$$

(B) GRAVITATIONAL FIELD

$$\phi(0, t) = \phi_0(t) + r^2 \phi_2(t) + O(r^4)$$

• BARDEEN: PIRANI: REGULARITY \Rightarrow ALL TENSOR COMPONENTS CAN BE EXPANDED IN NON-NEG. POWERS OF x, y, z :

$$x = r \sin \theta \cos \varphi \quad y = r \sin \theta \sin \varphi \quad z = r \cos \theta$$

• APPLYING TO OUR CASE (WITH ASSUMPTION OF STRONG COORDS) FIND

$$g(0, t) = g_0(t) + r^2 g_2(t) + \dots$$

WHERE g IS ANY OF a, b, K^r OR K^e

$$\rightarrow a'(0, t) = b'(0, t) = K^r'(0, t) = K^e'(0, t) = 0 \quad (43a-d)$$

• THESE CONDITIONS WILL BE CONSISTENT WITH EVOL. EQUIS ONLY IF

$$\alpha'(0, t) = \beta(0, t) = 0 \quad (44)$$

$$\beta(0, t) = r \beta_2(t) + O(r^3)$$

(SMOOTHNESS OF COORDINATES)

• LOCAL FLATNESS: CONSIDER A TRANSPORT OF AN ARBITRARY VECTOR ABOUT CLOSED LOOP ENCLORING

$r=0$ on $\theta = \frac{\pi}{2}$ (EQUATORIAL PLANE); DEMAND THAT
 THERE BE NO NET FLOW IN LIMIT LOOP SHRUNK TO
 POINT $\equiv \lim_{r \rightarrow 0} \int_{\text{PROPER CIRCUM}} / \text{PROPER RADIUS} = 2\pi$
 FIND

$$\nabla^r(rb) \nabla_r(rb) = -1$$

USING PREVIOUS RESULTS INCLUDING ABOVE REG. CONDITIONS
 FIND

$$a(0,t) = b(0,t) \quad (45)$$

THIS + \dot{a}, \dot{b} EGNS + REG. THEN IMPLY

$$K^r_r(0,t) = K^e_e(0,t) \quad (46)$$

* NOTE: REGULARITY CONDITIONS MUCH MORE INVOLVED
 FOR AXISYMMETRY; MAINTAINING REGULARITY IN AXI.
 SIMULATIONS ALSO MUCH MORE PROBLEMATIC THAN S.S.

TRAPPED SURFACES / APPARENT HORIZONS

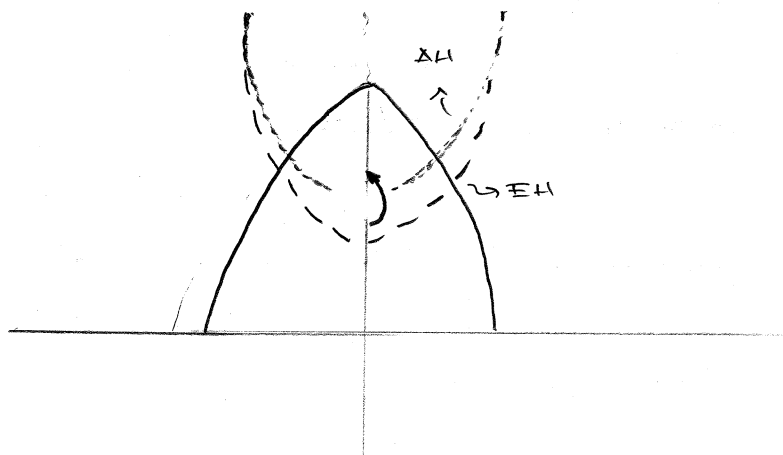
* WANT TO STUDY BLACK HOLE FORMATION; BH CHARACTERIZED
 BY AN EVENT HORIZON WHICH CAN ONLY BE DETERMINED
 ONCE COMPLETE S.T. HAS BEEN CONSTRUCTED

* USEFUL TO BE ABLE TO COMPUTE "INSTANTANEOUS" APPEN.
 (I.E. ON ANY HYPERSURFACE $\Sigma(t)$) TO EH. —
 PROVIDED BY APPARENT HORIZON \equiv OUTERMOST
MARGINALLY TRAPPED SURFACE

• TRAPPED SURFACE: 2-SURFACE WITH TOPOLOGY S^2 SUCH THAT DIVERGENCE OF OUTGOING NULL GEODESICS EMANATING FROM SURFACE < 0

• MARGINALLY TRAPPED SURFACE: " < 0 " \rightarrow " $= 0$ "

• MODULO COSMIC CENSORSHIP (NO NAKED SINGULARITIES)
EXISTENCE OF $\Delta H \Rightarrow$ EXISTENCE OF EH ; HOWEVER
CAN HAVE EH WITHOUT ΔH



• WILL TEND TO USE TERMS ΔH , IS ; ITS INTER-
CHANGEABLE, BUT SHOULD BE AWARE OF DISTINCTIONS

(MARGINALLY) TRAPPED SURFACE EGM (ΔH EGM)

• CONSIDER A 2-SURFACE WITH OUTGOING NULL
TANGENT u^a WHICH IS MARGINALLY TRAPPED,
THEN

$$\nabla_a u^a = 0$$

NOW, CAN WRITE u^a AS

$$u^a = s^a + n^a$$

$\left(\begin{array}{l} \hookrightarrow \text{UNIT FUTURE-DIRECTED TIMELIKE NORMAL TO } \Sigma \\ \hookrightarrow \text{UNIT OUTWARDS-POINTING SPACELIKE NORMAL TO 2-SURF.} \end{array} \right.$

IN $3+1$ DECOMPOSITION, METRIC h_{ab} , h^{ab} IS INDUCED ON THE 2-SURFACE BY PROJECTION

$$h^{ab} = \gamma^{ab} - s^a s^b = g^{ab} + n^a n^b - s^a s^b$$

CAN SHOW (EXERCISE) THAT $\nabla_a u^a$ IS A "2-VECTOR"; I.E. IS INTRINSIC TO 2-SURFACE; I.E. DOES NOT DEPEND ON HOW 2-SURFACE IS EMBEDDED IN Σ , THEN

$$\nabla_a u^a = g^{ab} \nabla_a u_b = h^{ab} \nabla_a u_b$$

$$= h^{ab} \nabla_a (s_b + n_b)$$

$$= h^{ab} \perp \nabla_a (s_b + n_b)$$

$$= h^{ab} (D_a s_b + \perp \nabla_a n_b)$$

$$= h^{ab} (D_a s_b - K_{ab})$$

$$= (g^{ab} - s^a s^b) (D_a s_b - K_{ab})$$

$$= D^a s_a - K + s^a s^b K_{ab}$$

$$(s^b D_a s_b = \frac{1}{2} D_a (s^b s_b) = \frac{1}{2} D_a (1) = 0)$$

h^{ab} PROJECTS OUT TO 2-SURFACE, SO CAN FIRST PROJECT OUT Σ

THUS, OUR TRAPPED SURFACE (ΔH) EQUATION IS

$$\boxed{D^a s_a - K + s^a s^b K_{ab} = 0} \quad (47)$$

AND ARGUING AS WE DID FOR THE 3+1 EQUIS WE GET A VALID COMPONENT PART OF THIS EQUATION BY TAKING $a \rightarrow i, b \rightarrow j$

$$\boxed{D^i s_i - K + s^i s^j K_{ij} = 0} \quad (48)$$

SPECIALIZING NOW TO SPHERICAL SYMMETRY

$$ds^2 = a^2 dr^2 + r^2 b^2 d\Omega^2$$

$$r_{ij} s^i s^j = 1 \rightarrow s^i = (a^{-2}, 0, 0)$$

$$D_i s^i = r^{-\frac{1}{2}} \partial_i (r^{\frac{1}{2}} s^i) \quad v^i = ar^2 b^2$$

$$= \frac{1}{ar^2 b^2} (r^2 b^2)' = \frac{2(rb)'}{arb}$$

THUS, (48) BECOMES

$$\frac{2(rb)'}{arb} - (K^r_r + 2K^{\theta}_{\theta}) + a^{-2} K^m_m = 0$$

↳ K^r_r

$$\boxed{(rb)' = arb K^{\theta}_{\theta}} \quad (49)$$

NOW, RECALL EVOL. EQU. (39) FOR b

$$\dot{b} = -\alpha b K^e + \frac{\beta}{r} (rb)'$$

$$\Rightarrow K^e = -(\alpha b)^{-1} \left(\dot{b} - \frac{\beta}{r} (rb)' \right)$$

$$rK^e = -(\alpha b)^{-1} \left((rb) \dot{} - \beta (rb)' \right)$$

SO (49) CAN BE REWRITTEN AS

$$\boxed{(rb) \dot{} + \left(\frac{\alpha}{a} - \beta \right) (rb)' = 0} \quad (50)$$

WHICH SAYS THAT THE SURFACE OF CONSTANT AREAL RADIUS $R \equiv rb$ IS OUTGOING NULL AT THE HORIZONTALLY TANGENT SURFACE IN ACCORD WITH OUR PHYSICAL PICTURE

COORDINATE CONDITIONS FOR S.S. SYSTEMS

NOT EXHAUSTIVE, WILL COVER MOST OF COMMON CHOICES

(A) SLICING CONDITIONS

(i) VIA CONDITIONS ON $T_{\mu\nu} K = K = K^i_i$

TAKE TRACE OF (12) (IN S.S.)

$$\dot{K} = \beta K' - D^i D_i \alpha + \alpha (R + K^2 + 4\pi(S-3J))$$

CAN ELIMINATE R (EXPENSIVE TO EVALUATE, NOT SO CRUCIAL HERE) USING HAMILTONIAN CONSTRAINT

$$R = K^i_j; K^j_i - K^2 + 16\pi\rho$$

$$\rightarrow \dot{K} = \beta K' - D^i D_i \alpha + \alpha (K^i_j; K^j_i + 4\pi(S+\rho)) \quad (51)$$

(ia) MAXIMAL SLICING $K = 0$ (LICHTEROWICZ)

IMPLEMENT BY CHOOSING COMPATIBLE $\Sigma(t)$

$$K(r, 0) = 0$$

THEN IMPOSE

$$\dot{K}(r, t) = 0 \quad t > 0$$

THESE (51) CAN BE VIEWED AS ELLIPTIC EQN FOR LAPSE

$$D^i D_i \alpha = \alpha (K^i_j; K^j_i + 4\pi(S+\rho)) \quad (52)$$

(ib) POLAR SLICING $K = K^r_r$ (BARDEEN; PIRANI)

$$K = K^r_r + \sum K^e_e = K^r_r \Rightarrow K^e_e = 0$$

AGAIN, IMPLEMENT BY CHOOSING $\Sigma(t)$ SO THAT

$$K^e_e(r, 0) = 0$$

THEN DEMAND

$$\dot{K}_e^e(r, t) = 0 \quad + \gamma > 0$$

RECALL EQN (36) FOR \dot{K}_e^e

$$\dot{K}_e^e = \beta K_e^e + \frac{\alpha}{(rb)^2} - \frac{1}{\alpha(rb)^2} \left(\frac{\alpha rb (rb)'}{a} \right)' + \alpha K K_e^e$$

USING $K_e^e = \dot{K}_e^e = K_e^e' = 0$, THIS BECOMES A FIRST-ORDER HOMOGENEOUS ODE FOR α

$$\boxed{\left(\frac{\alpha rb (rb)'}{a} \right)' - \alpha a = 0} \quad (93)$$

(ii) INGOING EDDINGTON-FINKELSTEIN TIME

DEMAND THAT t BE CHOSEN SO THAT $\frac{\partial \rho}{\partial t} - \frac{\partial \rho}{\partial r}$ IS NULL

$$g_{\mu\nu} \left(\frac{\partial x^\mu}{\partial t} - \frac{\partial x^\mu}{\partial r} \right) \left(\frac{\partial x^\nu}{\partial t} - \frac{\partial x^\nu}{\partial r} \right) = 0$$

$$g_{tt} - 2g_{rt} + g_{rr} = 0$$

$$(-\alpha^2 + a^2 \beta^4) - 2a^2 \beta + a^2 = 0$$

$$-\alpha^2 + a^2 (1 - \beta)^2 = 0$$

ASSUMING $\beta < 1$

$$\boxed{\alpha = a(1 - \beta)} \quad (94)$$

(1) "ALGEBRAIC CONDITION"

* NOTE THAT WE COULD ALSO HAVE DERIVED (54) FROM OUR PREVIOUS CALC. OF CHAR. DIRECTIONS

$$-\frac{1}{a} = \frac{dr}{dt_{\text{ingoing}}} = -\beta - \frac{\alpha}{a} \rightarrow \alpha = a(1 - \beta)$$

(B) SPATIAL COORDINATE CONDITIONS

(i) SPATIAL COORDINATES: $\beta = 0$

(ii) AREAL COORDINATE

* DEMAND THAT r MEASURE PROPER SURFACE AREA

$\rightarrow b(r, t) \equiv \frac{1}{2}$; AS USUAL, IMPLEMENT VIA $b(r, 0) = \frac{1}{2}$, $\dot{b}(r, t) = 0$, RECALL \dot{b} EQN

$$\dot{b} = -\alpha b K^e_e + \frac{\beta}{r} (rb)'$$

SO THE SPAT COORDINATE MUST SATISFY

$$\beta = \alpha r K^e_e$$

(55)

(iii) ISOTROPIC (SOMETIMES ISOTHERMAL) COORDINATES

* DEMAND THAT 3-METRIC BE CONFORMALLY FLAT

$$ds^2 = a^2(dr^2 + r^2 d\Omega^2)$$

ONCE AGAIN, IMPLEMENT BY SPECIFYING

$a(r, t) = b(r, t)$ THEN DEMAND

$$\dot{a}(r, t) = \dot{b}(r, t)$$

$$\dot{a} = -\alpha a K^r_r + (a \beta)'$$

$$\dot{b} = -\alpha b K^e_e + \frac{\beta}{r} (r b)'$$

EQUATING THE RHS'S AND USING $b = a$

$$-\alpha a K^r_r + a' \beta + a \beta' = -\alpha a K^e_e + \beta a' + \frac{\beta}{r} a$$

$$\beta' - \frac{\beta}{r} = \alpha (K^r_r - K^e_e)$$

$$\left(\frac{\beta}{r} \right)' = \frac{\alpha (K^r_r - K^e_e)}{r} \quad (56)$$

EXAMPLE of GENERAL CLASS of CONDITIONS CALLED
 "MINIMAL DISTORTION" (YORK; OTURCHADHA (1974),
 DUL. J.A. AMS. SOC. 19, 509; SEE ALSO ARTICLE IN "SURFES ..."
 STARR ed.), SO CALLED SINCE THEY TRIVITIZE "STRETCHING"
 of COORDINATE ELLIPSOIDS IN MOVING FROM $\Sigma(t) \rightarrow \Sigma(t+dt)$

MINIMAL DISTORTION Eqn

$$(\Delta_r \beta)^i = 2 D_j \left(\alpha (K^{ij} - \frac{1}{3} \delta^{ij} K) \right) \quad (57)$$

WHERE $(\Delta_r \beta)^i \equiv D_j (\beta)^{ij}$ IS THE VECTOR
 LAPLACIAN DEFINED PREVIOUSLY IN THE IVP DISCUSSION

EMKC EQU'S IN SOME SPECIFIC COORDINATE SYSTEMS

- * A) POLAR / IDEAL (POLAR/RADIAL, CELL. & SCHWARZ)
- B) MAXIMAL / ISOTROPIC
- (C) MAXIMAL / IDEAL)
- D) IEE

A) POLAR / IDEAL

i) α : $K = K^i_j = K^r_r$

POLAR SLICING

ii) β : $b = \underline{r}$ ($r_b = r$)

IDEAL COORDINATE

= RECALL SINCE $K = K^r_r + 2K^\theta_\theta$; $K = K^r_r \Rightarrow K^\theta_\theta = 0$

o IDEAL CONDITION FOR SHIFT (55) (DERIVED FROM $\dot{\beta} = 0$)

$$\beta = \alpha r K^\theta_\theta \Rightarrow \boxed{\beta = 0} \quad (56)$$

o THUS THE 4-METRIC IS DIAGONAL IN THIS CASE (ALTERNATE DERIVATION OF POLAR SLICING EEM IN SPH. SYMM. ($\dot{\beta} = \underline{r}$, $\beta = 0$))

$$ds^2 = -\alpha^2(r,t) dt^2 + a^2(r,t) dr^2 + r^2 d\Omega^2 \quad (59)$$

$$K^i_j = \text{diag}(K^r_r, 0, 0) \quad (60)$$

WE HAVE CONSIDERABLE SIMPLIFICATION OF EQNS OF MOTION
(MAY BE MOTIVATED FOR COMPUTATIONAL USE)

CONSTRAINT EQUATIONS

i) HAMILTONIAN CONSTRAINT

$$R = 4K^r r K^{\theta} + 2K^{\theta}{}^2 = 16\pi\rho$$

$$\rightarrow R = 16\pi\rho$$

FROM GENERAL EXPRESSION FOR R WITH $b=1$

$$R = \frac{4}{r} \frac{a'}{a^3} + \frac{2}{r^2} (1 - a^{-2}) \quad (61)$$

NOW, IN ANALOGY WITH VACUUM SCHWARZ. SOLN. DEFINE
MASS ASPECT Fcn, $m(r,t)$ VIA

$$\left(\frac{1 - \frac{2m(r,t)}{r}}{r} \right)^{-1} = a(r,t)^2 \quad (62)$$

OR

$$m = \frac{1}{2} r (1 - a^{-2}) \quad (63)$$

THEN AN EASY CALCULATION SHOWS THAT

$$m' = \frac{dm}{dr} = \frac{1}{4} r^2 R \quad (64)$$

THUS, THE HAMILTONIAN CONSTRAINT IN THE P/A SYSTEM,
FOR A GENERAL SPHERICALLY SYMMETRIC SOURCE
CAN BE WRITTEN.

$$\frac{dm}{dr} = 4\pi r^2 \rho$$

(61)

- HOWEVER, AS WE DISCUSSED LAST TIME, THE FAMILIAR (INTUITIVE) APPEARANCE OF THIS EQUATION IS LARGELY A CONSEQUENCE OF OUR SPECIFIC CHOICE OF COORDINATES
- MASS ASPECT IS PHYSICALLY SIGNIFICANT, THOUGH SINCE WHERE $T_{ab} = 0$, OUR S.P. MUST BE A PIECE OF SCHWARZSCHILD

$$ds^2 = -\left(1 - \frac{2M}{r}\right) dt^2 + \left(1 - \frac{2M}{r}\right)^{-1} dr^2 + r^2 d\Omega^2$$

I.E. WHERE $T_{ab} = 0$ WE MUST HAVE $m(r, t) = \text{constant} = M = \text{TOTAL GRAVITATING MASS CONTAINED WITHIN SPHERE OF RADIUS } r \text{ AT TIME } t$. WHERE $T_{ab} \neq 0$ ($\rho \neq 0$), INTERPRETATION OF $m(r, t)$ NOT SO CLEAR CUT, BUT FOR DIDACTIC PURPOSES, THERE IS NO HARM IN REGARDING IT AS A "MASS"

- AS WRITTEN, (61) NOT ENTIRELY CONVENIENT FOR NUMERICAL WORK - ρ WILL GENERALLY DEPEND IMPLICITLY ON $m(a)$ - IN ERKA CASE

$$\rho = \frac{1}{2} a^{-2} (\dot{\Phi}^2 + \dot{\Pi}^2)$$

BETTER TO WRITE AS EXPLICIT, NON-LINEAR CASE FOR a

$$R = 16T\omega \Rightarrow \frac{4}{r} a^1 + \frac{1}{2} (1 - a^{-2}) = 16T\omega$$

$$\left(\times \frac{a^2 r}{4} \right)$$

$$\boxed{\frac{a^1}{a} + \frac{a^2 - 1}{2r} - 4T\omega a^2 \omega^2 = 0} \quad (62)$$

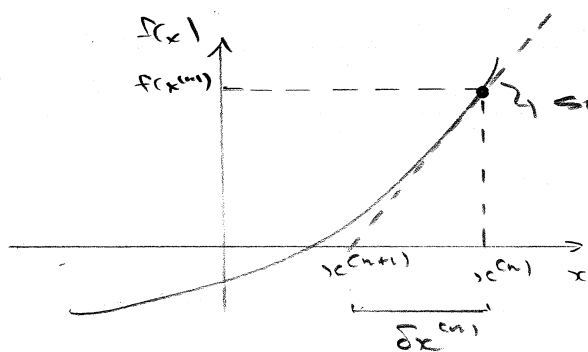
OR FOR THE EMKA SYSTEM

$$\boxed{\frac{a^1}{a} + \frac{a^2 - 1}{2r} - 2T\omega \left(\frac{1}{a^2} + \pi^2 \right) = 0} \quad (63)$$

SOLUTION OF (62) AND LIKE USING $O(h^2)$ F.D. AND NEWTON'S METHOD

RECALL NEWTON'S METHOD FOR SINGLE NON-LINEAR EQN $f(x) = 0$ IN SINGLE UNKNOWN x

SEEK x^* SATISFYING $f(x^*) = 0$ ITERATIVELY, I.E. START WITH INITIAL ESTIMATE $x^{(0)}$, THEN GENERATE ITERATES $x^{(1)}, x^{(2)}, \dots, x^{(n)}, x^{(n+1)}, \dots$ SUCH THAT $\lim_{n \rightarrow \infty} x^{(n)} = x^*$



TERMINOLOGICAL $r^{(n)} \equiv f(x^{(n)})$
 (RESIDUAL)
 $r^{(n)} \rightarrow 0$ AS $n \rightarrow \infty$

$$\boxed{x^{(n+1)} = x^{(n)} - \delta x^{(n)} \quad \text{WHERE}$$

$$\delta x^{(n)} = \frac{f(x^{(n)})}{f'(x^{(n)})} = \frac{r^{(n)}}{f'(x^{(n)})}$$

STOPPING CRITERIA: TYPICALLY ITERATE UNTIL

$$1a) \frac{|f'(x^{(n)})|}{|x^{(n)}|} \leq \epsilon_{\delta x} \quad \text{— USER SPECIFIED THRESHOLD}$$

TYPICALLY WANT \ll F.D.
SOLUTION ERROR $|u^k - u| / |u|$

$$1b) |f^{(n)}| \leq \epsilon_f$$

TRUNCATION ERROR $L^k u$
WHERE L IS D.E.

OR

$$2) \text{ DIVERGENCE DETECTED: } \delta x^{(n+2)} > \delta x^{(n+1)} > \delta x^{(n)}$$

WILL GENERALLY SUFFICE

$$3) n > n_{\max} \rightarrow \text{USER SPECIFIED (50),}$$

(TYPICALLY WILL REQUIRE ONLY FEWER)

NOTE: WHEN IT CONVERGES, NEWTON'S METHOD CONVERGES QUADRATICALLY, I.E.

$$\lim_{n \rightarrow \infty} \frac{r^{(n+1)}}{r^{(n)}} = \lim_{n \rightarrow \infty} \frac{\frac{\delta x^{(n+1)}}{\delta x^{(n)}}}{\frac{\delta x^{(n)}}{\delta x^{(n-1)}}} = 2$$

SHOULD ALWAYS EXPECT/DEMAND THIS BEHAVIOUR IN PRACTICE SINCE WILL GENERALLY ONLY BE ACHIEVED IF BOTH $f(x^{(n)})$, $f'(x^{(n)})$ COMPUTATIONS ARE CORRECT

END NEWTON'S METHOD ASIDE

A NOT IDEAL WBL COMPUTATIONALLY $\alpha^2 = 1$
ETC CAN LEAD TO "CATASTROPHIC LOSS OF PRECISION"

FOR $a \geq 1$ (NEAR FLAT-SPACE!!). RECAST (63) IN
 NEW VAR, A

$$A \equiv \ln a \quad a = e^A$$

WE THEN HAVE

$$A' + \frac{e^{2A} - 1}{2r} - 2\pi r (\bar{\Phi}^2 + \pi^2) = 0 \quad (6A)$$

DISCRETIZATION: DEFINE DISCRETE OPERATORS Δ_r^+ , μ_r^+ VIA

$$\begin{aligned} \Delta_r^+ f(r) &\equiv (\Delta r)^{-1} (f(r + \Delta r) - f(r)) \\ &= f'(r + \frac{\Delta r}{2}) + O(\Delta r^2) \end{aligned}$$

$$\begin{aligned} \mu_r^+ f(r) &\equiv \frac{1}{2} (f(r + \Delta r) + f(r)) \\ &= f(r + \frac{\Delta r}{2}) + O(\Delta r^2) \end{aligned}$$

AND DEFINE μ_r^+ (UNLIKE RIPL OPERATORS (WARNING!!))
 TO HAVE PRECEDENCE OVER ALL ALGEBRAIC & FUNCTIONAL
 OPERATIONS; E.G. SO

$$\mu_r^+ \left(\frac{f^2 g}{h} \right) = \frac{[\mu_r^+(f)]^2 \mu_r^+(g)}{\mu_r^+(h)}$$

THEN THE FOLLOWING IS ALL $O(h^2) = O(\Delta r^2)$ DISCRETIZATION of (6A)

$$\Delta_r^+ A + \frac{2(\mu_r^+ A)}{2r} - 1 - 2\pi \mu_r^+(r (\bar{\Phi}^2 + \pi^2)) = 0 \quad (6B)$$

OR USING CONVENTIONAL INDEX NOTATION (NOTE: WE'RE ASSUMING A UNIFORM SPATIAL MESH $r_j = j \Delta r$)

$$(\Delta r)^{-1} (A_{j+1} - A_j) + \frac{A_{j+1} + A_j}{2r_{j+\frac{1}{2}}} - 2\pi r_{j+\frac{1}{2}} (\bar{\Phi}_{j+\frac{1}{2}}^2 + \pi_{j+\frac{1}{2}}^2) = 0 \quad (65')$$

WHERE, E.G., $\bar{\Phi}_{j+\frac{1}{2}} \equiv \frac{1}{2} (\bar{\Phi}_{j+1} + \bar{\Phi}_j)$

(65') IS OF THE FORM $f(A_{j+\frac{1}{2}}) = 0$, SO CAN SOLVE VIA NEWTON'S METHOD OUTLINED ABOVE WITH

$$f'(A_{j+\frac{1}{2}}^{(n)}) = (\Delta r)^{-2} + \frac{A_j + A_{j+1}}{2r_{j+\frac{1}{2}}} \quad (66)$$

• INTEGRATE (65') OUTWARDS FROM $r=0$ STARTING WITH THE INITIAL CONDITION (ASSUMING $r_1 = 0$)

$$A_1 = 0$$

WHICH FOLLOWS FROM ELEMENTARY FLATNESS AT $r=0$.
 $a(0, t) = b(0, t) = 1 \Rightarrow A(0, t) = 0$, THEN SOLVING EACH OF $f(A_{j+\frac{1}{2}}) = 0$, $j = 1, \dots, n-1$ IN TURN USING NEWTON'S METHOD ("POINT-WISE NEWTON ITERATION")
NOTE: INWARDS INTEGRATION IS (NUMERICALLY) UNSTABLE. FINALLY, SET $a_j = \exp A_j$

• ONE LAST COMMENT ON HAMILTONIAN CONSTRAINT

FOR EMKA:

SUCCESSFUL TOP INITIAL GUESSES.

(1) $A_{j+1}^{(0)} = A_j$

(2) USE 2 EQUATION

(2) $A_{j+1}^{(0)} = 2A_j - A_{j-1}$

(3) DISCRETIZE (2) USING A_j IN "SOURCE TERMS"

$$\frac{dm}{dr} = 4\pi r^2 \rho = 2\pi r^2 \left(\frac{\bar{\rho}^2 + \pi^2}{a^2} \right) > 0$$

→ HAVE EASY DEMONSTRATION OF POSITIVITY OF GRAV. MASS IN THIS SYSTEM

ii) MOMENTUM CONSTRAINT

GENERAL:

$$K^e_e + \left(\frac{rb}{r}\right)' (K^e_e - K^r_r) = -4\pi j_r \quad (62)$$

SO WITH $K^e_e = 0$, $b=1$ THIS BECOMES AN ALGEBRAIC (!!) EQU FOR K^r_r

$$K^r_r = 4\pi r j_r \quad (63)$$

AND FOR THE ERKA SYSTEM

$$K^r_r = -4\pi r \frac{\bar{\rho} \pi}{a} \quad (64)$$

INITIAL DATA

• IT IS NOW EASY TO SEE HOW AN AD HOC PROCEDURE FOR DETERMINING INITIAL DATA PROCEEDS IN THE (P)R SYSTEM. FROM (63) AND (64) WE SEE THAT WE CAN SIMPLY SPECIFY

$$\bar{\rho}(r, 0), \pi(r, 0)$$

FREELY, THEN SOLVE (63) FOR a , K^r_r IS IMMEDIATELY GIVEN BY (64)

FIRST WENT TO WRITE DOWN MORE GENERAL FORM OF K^e_e EGM (36) WHICH MADE USE OF SPECIFIC FORM OF T_{ab} FOR MASSLESS SCALAR FIELD. GENERAL FORM (USEFUL FOR PROJ 3, TERM PROJECTS) IS

$$K^e_e = \rho K^e_e + \frac{\alpha}{(rb)^2} - \frac{1}{a(rb)^2} \left(\frac{\alpha rb}{a} (rb)' \right)' + \alpha (K K^e_e + 4\pi (S^r_r - \rho)) \quad (36')$$

POLAR SLICING CONDITION FOLLOWS FROM SETTING $K^e_e = K^e_e = K^e_e' = 0$, $b = r$; THEN WE FIND

$$\frac{\alpha'}{\alpha} - \frac{a'}{a} + \frac{1-a^2}{r} + 4\pi r a^2 (\rho - S^r_r) = 0 \quad (70)$$

BUT FROM HAM. C. (62) WE HAVE

$$\frac{a'}{a} = \frac{1-a^2}{2r} + 4\pi r a^2 \rho$$

SO OUR SLICING EGM BECOMES

$$\frac{\alpha'}{\alpha} - \frac{a^2-1}{2r} - 4\pi r a^2 S^r_r = 0 \quad (71)$$

AND FOR THE EMKA SYSTEM, $S^r_r = \rho = \frac{1}{2} a^{-2} (\mathbb{E}^2 + \Pi^2)$

SO

$$\frac{\alpha'}{\alpha} - \frac{a^2-1}{2r} - 2\pi r (\mathbb{E}^2 + \Pi^2) = 0 \quad (92)$$

DEFINING $L \equiv \ln \alpha$, WE HAVE

$$\begin{aligned} L' + g_0 &= 0 \\ g_0 &= - \left(\frac{\alpha^2 - 1}{2r} + 2\pi r (\Phi^2 + \Pi^2) \right) \end{aligned} \quad (73)$$

AND A SECOND ORDER FD APPROX IS

$$\Delta_r^2 L + \mu_r^2 g_0 = 0$$

$$\Delta_r^{-1} (L_{j+1} - L_j) + \frac{1}{2} (g_{0,j+1} + g_{0,j}) = 0$$

$$\rightarrow L_j = L_{j+1} + \frac{\Delta r}{2} (g_{0,j+1} + g_{0,j})$$

WHICH, GIVEN A B.C. AT $r = r_{\max}$, CAN EASILY BE INTEGRATED INWARDS (COULD ALSO INT. OUT. FROM $r=0$), SETTING $T_{ab} = 0$ AT $r = r_{\max}$, AND DEMANDING THAT $\dot{\alpha}$ MEASURE PROPORTION OF COORD. STAT. OBS. AS $r \rightarrow \infty$, COMPARISON WITH SCHWARZ. LINE ELEMENT YIELDS

$$\alpha(r_{\max}, t) = \frac{1}{a(r_{\max}, t)} \quad (74)$$

EVOLUTIONAL EQUATIONS

GEOMETRY (FROM GEN EINS (33)-(35))

$$\dot{\alpha} = -\alpha a K_r^r \quad (75)$$

$$\dot{K}_r^r = -\frac{1}{a} \left(\frac{\dot{\alpha}}{\alpha} \right)' - \alpha \left(\frac{2}{a r} \left(\frac{1}{r} \right)' + 8\pi \frac{1}{a^2} \right) \quad (76)$$

RECALLING MAX CONS (69)

$$K_r = -4\pi r \frac{\Phi}{a}$$

WE CAN ALSO WRITE

$$\ddot{a} = 4\pi r \frac{\Phi}{a}$$

(77)

SCALAR FIELD (FROM GEN. EQNS (37) - (3E))

$$\dot{\Phi} = \left(\frac{\Phi}{a} \right)'$$

(78)

$$\ddot{\Phi} = \frac{1}{r^2} \left(r^2 \frac{\Phi}{a} \right)' = \frac{3}{2(r^2)} \left(r^2 \frac{\Phi}{a} \right)$$

(79)

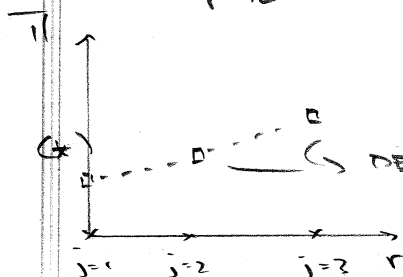
MOTIVATION FOR $r^{-2} \frac{\partial}{\partial r} \rightarrow \frac{3}{2} \frac{\partial}{\partial (r^2)}$: IMPROVED REG.

AT $r=0$

$$r^2 \frac{\Phi}{a} \sim r^3 \text{ AS } r \rightarrow 0$$

DIFFERENCING NOTE: $\ddot{\Phi}$ EQN NAIVELY SINGULAR AT $r=0$, COULD REGULARIZE VIA L'HOPITAL'S RULE, ALTERNATE STRATEGY MAKES USE OF

$$\lim_{r \rightarrow 0} \Phi(r, t) = \Phi_0(t) + r^2 \Phi_2(t)$$



(DETERMINED VIA DISCRETE VERSION of (79))

*) DETERMINED VIA "QUADRATIC EQN"

$$\pi_2 = \frac{1}{3} (4\pi_2 - \pi_3)$$

UPDATE SCHEME

• CLEARLY, WOULD BE PERVERSE TO USE K^r EV. EQU INSTEAD OF (ALGEBRAIC) MOT CONS. WHICH EFF. ELIMINATES K^r .

• COULD USE \dot{a} EQU RATHER THAN HAZ CONTS TO UPDATE a , BUT

- a) NEED H.C. SOLVER AT $t=0$ ANYWAY
- b) USING H.C. TENDS TO GIVE IMPROVED STABILITY

FULLY CONSTRAINED SCHEME (SEE ONLINE PAPER FOR PAPER 2)

$$\begin{aligned} \dot{\Phi} &= \left(\frac{\alpha}{a} \pi \right)' & \dot{\pi} &= 3 \frac{\partial}{\partial (r^2)} \left(r^2 \frac{K}{a} \Phi \right) \\ \frac{a'}{a} + \frac{a^2 - 1}{2r} - 2\pi r (\Phi^2 + \pi^2) &= 0 \\ \frac{a'}{a} - \frac{a^2 - 1}{a} - 2\pi r (\Phi^2 + \pi^2) &= 0 \end{aligned}$$

LIO AH'S IN DA COORDS

$$(rb)^\cdot = arb K^e \tag{19}$$

$t = 0!$ $r = \text{const}$ CAN NOT BECOME NULL

TIME LIKE DA CONSTRUCTION

SIGNATURE OF DA FLATNESS: $2m(r+1)/r \rightarrow 1$