Phy 329: Computational Physics Homework 5 Due: Monday, November 11, 3:00pm

The following assignment involves writing and testing three Fortran 77 programs which use finite-difference techniques to solve various problems. Do all development and execution on `einstein`*. As usual, all files required by the assignment must reside in the correct places on your SGI account for the homework to be considered complete. Contact me immediately if you are having undue difficulties with any part of the homework.*

Problem 1: In directory `~/hw5/a1` on your SGI account, create a source file `dpint.f` which defines a `real*8` function `dpint` having the following header:

```
real*8 function dpint(xto,x,f,n,rc)
   integer        n,       rc
   real*8         xto,     x(n),    f(n)
```

`dpint` is to return the value $p($`xto`$)$, where $p(x)$ is the polynomial of degree $n-1$ which interpolates the input (x, f) pairs $($`x(i)`$,$`f(i)`$)$, `i = 1 ... n`. `dpint` should use Neville's algorithm (class notes, October 16) to construct $p($`xto`$)$. The routine should also provide error checking (all error messages should be directed to `stderr`), and set the return code, `rc`, as follows:

- If $n > 20$, print an error message stating that the requested degree of polynomial interpolation is too large, set `rc = 2` and return. Such a restriction is needed since the routine will require internal storage to implement Neville's algorithm.
- If the `x(i)` are not distinct, print a suitable error message, set `rc = 3`, and return.
- If `xto` $<$ $\min_{\texttt{i}}$ `x(i)` or `xto` $>$ $\max_{\texttt{i}}$ `x(i)`, then set `rc = 1` to indicate that *extrapolation* is occuring and compute the value of $p($`xto`$)$ (don't print an error message in this case).
- Normal interpolation, set `rc = 0`.

Working in the same directory, write a driver program called `tdpint` (source file `tdpint.f`, executable `tdpint`) which has the following usage:

```
tdpint: <xto> [<xto> ...]
```

`tdpint` must accept up to 10 `xto` values on the command-line, then read up to 20 $($`x(i)`$,$`f(i)`$)$ pairs from standard input. It is to then evaluate the interpolating polynomial (which passes through the $($`x(i)`$,$`f(i)`$)$ pairs) for each of the `xto` and output $($`xto`$, p($`xto`$))$ (two `real*8` numbers per line) on standard output. If a return code other than 0 or 1 is encountered, the main program should write an appropriate message to standard error, then exit. Note that you may wish to make use of the routines `dvvto, dvvfrom` you wrote for Homework 3. Test your implementations of `tdpint` and `dpint` thoroughly, both for valid and invalid input: I will test your work using my own input.

Problem 2: Consider the equation of motion for the displacement, $q(t)$, of a simple harmonic oscillator with frequency ω:

$$\ddot{q} = -\omega^2 q \tag{2.1}$$

where an overdot denotes differentiation with respect to time, t. Given initial conditions

$$q(0) = q_0 \qquad \dot{q}(0) = \dot{q}_0$$

the subsequent motion of the oscillator is completely determined via (2.1). In directory `~/hw5/a2` on your SGI account, create a source file `sho.f` and corresponding executable `sho`, which solves this ordinary differential equation using a finite-difference technique. In particular, discretize time uniformly $(t^n = 0, \triangle t, 2\triangle t, 3\triangle t, \cdots)$ and use the usual second-order $(O(\triangle t^2))$ approximation of the second derivative, $\ddot{q}$ to derive a discrete equation of motion. This equation of motion should be of the form:

$$q^{n+1} = c_0\, q^n + c_1\, q^{n-1}$$

for some coefficients c_0, c_1, where $q^n \equiv q(n\triangle t)$. Your program must accept command-line arguments (most of which will have defaults) as illustrated by the following usage message:

```
usage: sho <q0> [<qdot0> <omsq> <tmax> <level> <olevel>]

 defaults          0.0    1.0    8.0      8       8
```

The command line arguments have the following interpretation (data types shown in parentheses):

- `q0, qdot0`: Initial oscillator position, $q(0)$ and velocity, $\dot{q}(0)$, respectively (`real*8`).
- `omsq`: Square of oscillator frequency (i.e. ω^2) (`real*8`).
- `tmax`: Maximum (final) integration time (`real*8`).
- `level`: Discretization level (`integer`). The integration interval `(0 ... tmax)` will be divided into `nt = 2**level + 1` time steps; thus $\triangle t = \texttt{tmax}/2^{\texttt{level}}$
- `olevel`: Output level (`integer`). Must not be greater than `level`. This parameter controls the frequency of output (time and position, as stipulated below) as follows:

  $$\texttt{ofreq} = 2^{\texttt{level - olevel}}$$

  Let `it` label the time step, with `it = 0, 1, ... nt - 1`. Then output is generated whenever

  $$\texttt{mod(it,ofreq)} \quad \texttt{.eq.} \quad \texttt{0}$$

  A key motivation for having this additional argument is to provide a mechanism to keep the specfic output times fixed (by keeping `olevel` fixed) as the resolution is increased (i.e. as `level` increases). Note that if `olevel .eq. level`, then output occurs every timestep; if `olevel .eq. level - 1`, output occurs every two timesteps, etc.

`sho` must periodically write the integration time, t^n, and computed oscillator position, q^n, to standard output (two numbers per line) as described above. It must also initialize q^0 and q^1 from the command-line values `q0`, `qdot0` to $O(\triangle t^3)$ (i.e. up to *and including* terms of $O(\triangle t^2)$) using the same Taylor series technique discussed in class for the wave equation (see the correction to Oct 23 notes which was distributed on Oct 25).

Convergence-test your program by performing the following runs

```
sho 1.0 0.0 1.0 8.0  8 8 > out8
sho 1.0 0.0 1.0 8.0  9 8 > out9
sho 1.0 0.0 1.0 8.0 10 8 > out10
```

Note that since the output level is fixed at 8, each of the output files `out8`, `out9`, `out10` should contain output at the same set of 257 times. Let q_l denote the level l solution. Demonstrate that your solution appears to be second order accurate by using `gnuplot` to graph $q_8 - q_9$ and $4(q_9 - q_{10})$ on the same plot. Save a postscript version of your plot in a file called `ctest.ps`.

Examine the output from

```
sho 1.0 0.0 1.0 512 8 8
sho 1.0 0.0 1.0 513 8 8
```

What happens to the estimated solution at level 8 when `tmax` > 512? What is the value of $\omega\triangle t$ when `tmax` $= 512$? (Answer these two questions in `~/hw5/a2/README`.)

Problem 3: In directory ~/hw5/a3 on your SGI account, create a source file `wave1d.f`, and corresponding executable `wave1d`, which uses second-order finite-difference techniques (as discussed in class) to solve the following one-dimensional wave equation for $u(x,t)$:

$$u_{tt} = u_{xx} \qquad 0 \le x \le 1 \quad t \ge 0 \tag{3.1}$$

$$u(x,0) = l(x) + r(x) \qquad u_t(x,0) = l'(x) - r'(x) \qquad u(0,t) = u(1,t) = 0 \tag{3.2}$$

where $l(x)$ and $r(x)$ are, respectively, the left-moving and right-moving components of the solution at $t = 0$ and $'$ denotes differentiation.

`wave1d` must accept 6 arguments as illustrated by the following usage message:

```
usage: wave1d <level> <dt/dx> <ncross> <a left-mover> <a right-mover> <olevel>
```

The arguments have the following interpretation:

- `level`: Discretization level (`integer`). The spatial mesh will have $\texttt{nx} = 2^{\texttt{level}} + 1$ points.
- `dt/dx`: "Courant number" (`real*8`). Ratio of temporal spacing $\triangle t$ to spatial mesh-size $\triangle x$.
- `ncross`: Final integration time in units of "crossing times" (`integer`). A crossing time is the amount of time it takes for a signal to propagate across the solution domain. Since the wave speed in (3.1) is 1, and the spatial domain is $0 \le x \le 1$, the crossing time in this case is also 1. Note that the number of time steps in the integration, `nt`, is then implicitly defined by `level`, `dt/dx` and `ncross`.
- `<a left-mover>`: The amplitude (`real*8`) of the initially left-moving component of the wave (see below).
- `<a right-mover>`: The amplitude (`real*8`) of the initially right-moving component of the wave (see below).
- `olevel`: Output level (`integer`). Must not be greater than `level`. This parameter defines the frequency of output as in the previous question:

  $$\texttt{ofreq} = 2^{\texttt{level} - \texttt{olevel}}$$

  In addition, in this case `ofreq` also specifies a "spatial" frequency of output, e.g. if `ofreq = 2`, then at output times, every second value $u_1^n, u_3^n, \cdots$ is dumped (see below).

To aid in the development of your program, the following routines are provided in the file ~phy329/hw5/a3/util.f

The first routine is

```
subroutine dvgaussian(g,dg,ddg,x,n,amp,x0,del)
   integer         n
   real*8          g(n),     dg(n),    ddg(n),    x(n)
   real*8          amp,      x0,       del
```

which given `x(j) , j = 1 ... n`, `amp`, `x0` and `del` returns a Gaussian profile, `g(j)`, and its first two derivatives, `dg(j)` and `ddg(j)`, evaluated on the finite-difference mesh:

$$\texttt{g(j)} \equiv g(\texttt{x(j)}) = \texttt{amp} \times \exp\left(-\left(\texttt{x(j)} - \texttt{x0}\right)^2 / \texttt{del}^2\right)$$

$$\texttt{dg(j)} \equiv \frac{dg}{dx}\left(\texttt{x(j)}\right)$$

$$\texttt{ddg(j)} \equiv \frac{d^2g}{dx^2}\left(\texttt{x(j)}\right)$$

This routine should be used to set up the initially left- and right-moving components of the solution, $l(x)$ and $r(x)$ as well as the first and second derivatives of these components, $l'(x), r'(x), l''(x), r''(x)$. Each of

the two components should be a Gaussian with `x0 = 0.5d0`, `del = 0.1d0` and an amplitude given by the corresponding command-line argument. The difference values u_j^0 and u_j^1 are to be initialized to $O(\triangle t^3)$ using the Taylor series approach discussed in class and mentioned in the previous question.

The second routine provided in `util.f` is

```
      subroutine gnuout(u,x,nx,t,stride)
         implicit       none

         integer        nx,           stride
         real*8         u(nx),        x(nx),        t

         integer        j

         do j = 1 , nx , stride
            write(*,*) t, x(j), u(j)
         end do
         write(*,*)

         return

      end
```

which writes data to standard output in `gnuplot splot`-format (see Oct 23 on-line notes). Assuming that the grid function `u` has been declared via

```
real*8 u(maxnx,2)
```

then the (only) output from your program should be generated every `ofreq` steps using a call like

```
call gnuout(u(1,np1),x,nx,t,ofreq)
```

When you are satisfied that your program is working, generate some sample output using:

```
wave1d 8 0.5 3 0.5 1.0 5 > out8
```

and then use `splot` in `gnuplot` to produce a surface plot of the results. Save a postscript version of your plot in the file `out8.ps`. Now try

```
 wave1d 8 1.00025 3 0.5 1.0 5 > out8uns
```

and use `gnplot` to make a postscript file `out8uns.ps` containing a surface plot of the results. What appears to be happening to the solution in this case? (Answer this question in `~/hw5/a3/README`.)